

1. Use the Gram-Schmidt process on \mathbf{R}^3 to orthonormalize the basis $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, $\begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 3 \\ -2 \\ 5 \end{bmatrix}$.
(Remember to clear fractions as you go and then normalize at the end.)

Call the given vectors $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$. Set $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$. Then

$$\mathbf{v}_2 = \mathbf{u}_2 - \frac{(\mathbf{u}_2, \mathbf{v}_1)}{(\mathbf{v}_1, \mathbf{v}_1)} \mathbf{v}_1 = \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} - \frac{-1}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1/3 \\ -2/3 \\ 1/3 \end{bmatrix}.$$

For convenience, we multiply by three to obtain

$$\mathbf{v}_2 = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}.$$

Now we have

$$\mathbf{v}_3 = \mathbf{u}_3 - \frac{(\mathbf{u}_3, \mathbf{v}_2)}{(\mathbf{v}_2, \mathbf{v}_2)} \mathbf{v}_2 - \frac{(\mathbf{u}_3, \mathbf{v}_1)}{(\mathbf{v}_1, \mathbf{v}_1)} \mathbf{v}_1 = \begin{bmatrix} 3 \\ -2 \\ 5 \end{bmatrix} - \frac{12}{6} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} - \frac{6}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}.$$

Thus an orthonormal basis is

$$\frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}.$$

2. Find a basis for \mathbf{R}^3 that includes the vectors $\begin{bmatrix} 2 \\ -2 \\ 6 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 1 \\ -3 \end{bmatrix}$.

We form the matrix

$$\begin{bmatrix} 2 & 0 & 1 & 0 & 0 \\ -2 & 1 & 0 & 1 & 0 \\ 6 & -3 & 0 & 0 & 1 \end{bmatrix}$$

and row reduce to obtain

$$\begin{bmatrix} 2 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 3 & 1 \end{bmatrix}.$$

If we divide the first row by 2 and the third by 3, we see that the initial 1s lie in columns 1, 2 and 4. Thus a basis is

$$\begin{bmatrix} 2 \\ -2 \\ 6 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

3. (a) Suppose $S = \{t, t - 3, t^2 + 1\}$ and $T = \{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$ are ordered bases for P_2 , and suppose the transition matrix from T to S is $P_{S \leftarrow T} = \begin{bmatrix} 2 & 4 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$. Find the basis T .

The j th column of $P_{S \leftarrow T}$ is the vector $[\mathbf{w}_j]_S$. Thus we have

$$\begin{aligned}\mathbf{w}_1 &= 2\mathbf{v}_1 + 1\mathbf{v}_2 + 0\mathbf{v}_3 = 2t + t - 3 = 3t - 3, \\ \mathbf{w}_2 &= 4\mathbf{v}_1 - 1\mathbf{v}_2 + 1\mathbf{v}_3 = 4t - (t - 3) + t^2 + 1 = t^2 + 3t + 4, \\ \mathbf{w}_3 &= 1\mathbf{v}_1 + 0\mathbf{v}_2 + 1\mathbf{v}_3 = t + t^2 + 1 = t^2 + t + 1.\end{aligned}$$

(b) Use $P_{S \leftarrow T}$ to find $[\mathbf{v}]_S$, given that $[\mathbf{v}]_T = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$.

This is the definition of what the transition matrix does, namely, $P_{S \leftarrow T}[\mathbf{v}]_T = [\mathbf{v}]_S$. Thus

$$[\mathbf{v}]_S = \begin{bmatrix} 2 & 4 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}.$$

4. State the Cauchy-Schwarz inequality for an arbitrary vector space V with inner product (\cdot, \cdot) .

$$|(\mathbf{u}, \mathbf{v})| \leq \|\mathbf{u}\| \|\mathbf{v}\|$$

5. Find the Fourier polynomial of degree two for the function $f(t) = \cos^2(t)$ with respect to the orthonormal basis

$$\left\{ \frac{1}{\sqrt{2\pi}}, \frac{1}{\sqrt{\pi}} \sin(t), \frac{1}{\sqrt{\pi}} \cos(t), \frac{1}{\sqrt{\pi}} \sin(2t), \frac{1}{\sqrt{\pi}} \cos(2t), \dots \right\}$$

using the following facts:

$$\begin{aligned}\int_{-\pi}^{\pi} \cos^2(t) dt &= \pi & \int_{-\pi}^{\pi} \cos^2(t) \sin(t) dt &= 0 & \int_{-\pi}^{\pi} \cos^3(t) dt &= 0 \\ \int_{-\pi}^{\pi} \cos^2(t) \sin(2t) dt &= 0 & \int_{-\pi}^{\pi} \cos^2(t) \cos(2t) dt &= \pi/2\end{aligned}$$

We know that we can write

$$\cos^2(t) \approx a_0 \frac{1}{\sqrt{2\pi}} + a_1 \frac{1}{\sqrt{\pi}} \sin(t) + b_1 \frac{1}{\sqrt{\pi}} \cos(t) + a_2 \frac{1}{\sqrt{\pi}} \sin(2t) + b_2 \frac{1}{\sqrt{\pi}} \cos(2t)$$

where the coefficients are expressed in terms of the given integrals. Because most of these integrals are zero, we have

$$\cos^2(t) \approx a_0 \frac{1}{\sqrt{2\pi}} + b_2 \frac{1}{\sqrt{\pi}} \cos(2t).$$

Now

$$a_0 = \int_{-\pi}^{\pi} \frac{1}{\sqrt{2\pi}} \cos^2(t) dt = \frac{1}{\sqrt{2\pi}} \int_{-\pi}^{\pi} \cos^2(t) dt = \frac{\pi}{\sqrt{2\pi}}.$$

Also,

$$b_2 = \int_{-\pi}^{\pi} \frac{1}{\sqrt{\pi}} \cos^2(t) \cos(2t) dt = \frac{\pi}{2\sqrt{\pi i}}.$$

Thus we obtain

$$\cos^2(t) \approx \frac{\pi}{\sqrt{2\pi}} \frac{1}{\sqrt{2\pi}} + \frac{\pi}{2\sqrt{\pi}} \frac{1}{\sqrt{\pi}} \cos(2t) = \frac{1}{2} + \frac{1}{2} \cos(2t).$$

Note that this is actually equality, as we have discovered a double angle formula the hard way.

6. Suppose we define a function $L: P_4 \rightarrow M_{22}$ by saying that

$$L(at^3 + bt^2 + ct + d) = \begin{bmatrix} a & b \\ c & d \end{bmatrix}.$$

Verify that L is an isomorphism by checking that it preserves the vector space operations (you may assume it is one-to-one and onto).

Pick two vectors in P_4 , say $\mathbf{u} = at^3 + bt^2 + ct + d$ and $\mathbf{v} = \alpha t^3 + \beta t^2 + \gamma t + \delta$. We need first to show that $L(\mathbf{u} + \mathbf{v}) = L(\mathbf{u}) + L(\mathbf{v})$. To this end, note that

$$\begin{aligned} L(\mathbf{u} + \mathbf{v}) &= L(at^3 + bt^2 + ct + d + \alpha t^3 + \beta t^2 + \gamma t + \delta) = \\ &L((a + \alpha)t^3 + (b + \beta)t^2 + (c + \gamma)t + (d + \delta)) = \begin{bmatrix} a + \alpha & b + \beta \\ c + \gamma & d + \delta \end{bmatrix}. \end{aligned}$$

On the other hand, we have

$$L(\mathbf{u}) + L(\mathbf{v}) = L(at^3 + bt^2 + ct + d) + L(\alpha t^3 + \beta t^2 + \gamma t + \delta) = \begin{bmatrix} a & b \\ c & d \end{bmatrix} + \begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix}.$$

These matrices are equal, so we have verified the first property.

For the second property, we need to show that $L(r\mathbf{u}) = rL(\mathbf{u})$, for any real number r . But we have

$$L(r\mathbf{u}) = L(r(at^3 + bt^2 + ct + d)) = L(rat^3 + rbt^2 + rct + rd) = \begin{bmatrix} ra & rb \\ rc & rd \end{bmatrix},$$

while

$$rL(\mathbf{u}) = rL(at^3 + bt^2 + ct + d) = r \begin{bmatrix} a & b \\ c & d \end{bmatrix}.$$

Again, these matrices are equal, so L is an isomorphism.

7. Suppose V is an inner product space. Show that if \mathbf{u} is orthogonal to each of $\mathbf{v}_1, \dots, \mathbf{v}_n$ in V , then \mathbf{u} is orthogonal to any vector in the subspace $W = \text{span}\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$.

Because \mathbf{u} is orthogonal to each \mathbf{v}_i , we know that $(\mathbf{u}, \mathbf{v}_i) = 0$ for each i . Pick a vector \mathbf{v} in W . Then $\mathbf{v} = a_1\mathbf{v}_1 + \dots + a_n\mathbf{v}_n$. We need to show that $(\mathbf{u}, \mathbf{v}) = 0$. But

$$(\mathbf{u}, \mathbf{v}) = (\mathbf{u}, a_1\mathbf{v}_1 + \dots + a_n\mathbf{v}_n) = a_1(\mathbf{u}, \mathbf{v}_1) + \dots + a_n(\mathbf{u}, \mathbf{v}_n) = 0.$$