

1. Prove the Pythagorean theorem: If  $\mathbf{u}$  and  $\mathbf{v}$  are orthogonal, then

$$\|\mathbf{u} + \mathbf{v}\|^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2.$$

Note that

$$\|\mathbf{u} + \mathbf{v}\|^2 = \langle \mathbf{u} + \mathbf{v}, \mathbf{u} + \mathbf{v} \rangle = \langle \mathbf{u}, \mathbf{u} \rangle + 2\langle \mathbf{u}, \mathbf{v} \rangle + \langle \mathbf{v}, \mathbf{v} \rangle$$

The fact that  $\mathbf{u}$  and  $\mathbf{v}$  are orthogonal means that  $\langle \mathbf{u}, \mathbf{v} \rangle = 0$ , so that the right side of the equation above becomes

$$\langle \mathbf{u}, \mathbf{u} \rangle + \langle \mathbf{v}, \mathbf{v} \rangle = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2.$$

2. Let  $V$  be the vector space of infinitely differentiable functions, and consider the linear operator  $L : V \rightarrow V$  given by

$$L(f(t)) = t^2 f''(t) - 4t f'(t).$$

Verify that the function  $f(t) = t - 3t^4$  is an eigenvector for this operator with corresponding eigenvalue  $\lambda = -4$

We need to check that

$$L(t - 3t^4) = -4(t - 3t^4).$$

But

$$L(t - 3t^4) = t^2(-36t^2) - 4t(1 - 12t^3) = -36t^4 - 4t + 48t^4 = 12t^4 - 4t = -4(t - 3t^4).$$

3. Let  $W$  be the subspace of  $P_2$  (with inner product  $\langle p(t), q(t) \rangle = \int_0^1 p(t)q(t) dt$ ) spanned by the orthogonal vectors  $p(t) = 1$  and  $q(t) = 2t - 1$ .

(a) Find a basis for  $W^\perp$ .

The vectors in  $W^\perp$  are those that are perpendicular to a basis for  $W$ . Thus the vector  $at^2 + bt + c$  is in  $W^\perp$  precisely if

$$0 = \langle at^2 + bt + c, 1 \rangle = \int_0^1 (at^2 + bt + c) dt = \frac{a}{3} + \frac{b}{2} + c,$$

and

$$0 = \langle at^2 + bt + c, 2t - 1 \rangle = \int_0^1 (2at^3 + (b - a)t^2 + (2c - b)t - c) dt = \frac{a}{6} + \frac{b}{6}.$$

Solving the corresponding system, we obtain

$$\left[ \begin{array}{ccc|c} \frac{1}{3} & \frac{1}{2} & 1 & 0 \\ \frac{1}{6} & \frac{1}{6} & 0 & 0 \end{array} \right] \rightsquigarrow \left[ \begin{array}{ccc|c} 2 & 3 & 6 & 0 \\ 0 & 1 & 6 & 0 \end{array} \right],$$

so the general solution is given by  $c = r$ ,  $b = -6r$ , and  $a = 6r$ . Choosing  $r = 1$ , we obtain the basis  $\{6t^2 - 6t + 1\}$ . (See part (c) for an alternative way to obtain a basis.)

(b) Find the projection of  $t^2$  onto  $W$ .

The basis we are given is orthogonal, so we plug into the formula to obtain

$$\begin{aligned}\text{proj}_W(t^2) &= \frac{\langle t^2, 1 \rangle}{\langle 1, 1 \rangle} 1 + \frac{\langle t^2, 2t-1 \rangle}{\langle 2t-1, 2t-1 \rangle} (2t-1) \\ &= \frac{\int_0^1 t^2 dt}{\int_0^1 1 dt} 1 + \frac{\int_0^1 (2t^3 - t^2) dt}{\int_0^1 (4t^2 - 4t + 1) dt} (2t-1) = \frac{1}{3} + \frac{1/6}{1/3} (2t-1) = t - \frac{1}{6}.\end{aligned}$$

(c) Write  $t^2$  as  $p(t) + q(t)$ , where  $p(t)$  is in  $W$  and  $q(t)$  is in  $W^\perp$ .

The projection of  $t^2$  onto  $W$  provides the  $W$  part of the expression. The  $W^\perp$  part is then just  $t^2$  minus the  $W$  part. So we have

$$t^2 = \left(t - \frac{1}{6}\right) + \left(t^2 - t + \frac{1}{6}\right).$$

Note that this automatically gives us a vector in  $W^\perp$ , namely  $t^2 - t + \frac{1}{6}$ . We know that  $W^\perp$  is 1-dimensional (because  $W$  is 2-dimensional and  $P_2$  is 3-dimensional), so this vector provides a basis for  $W^\perp$ .

4. Find an invertible matrix  $P$  and a diagonal matrix  $D$  so that  $P^{-1}AP = D$ , where

$$A = \begin{bmatrix} 2 & 0 & 0 \\ -4 & -4 & 2 \\ -8 & -12 & 6 \end{bmatrix}.$$

(You do **not** have to invert  $P$  or multiply anything out; just find  $P$  and  $D$ .)

For the eigenvalues, we compute the determinant of  $A - \lambda I$  as follows:

$$\det(A - \lambda I) = \det \begin{bmatrix} 2 - \lambda & 0 & 0 \\ -4 & -4 - \lambda & 2 \\ -8 & -12 & 6 - \lambda \end{bmatrix} = -\lambda^3 + 4\lambda^2 - 4\lambda = -\lambda(\lambda - 2)^2.$$

Thus the eigenvalues are  $\lambda = 0$  (once) and  $\lambda = 2$  (twice).

Now we find the eigenvectors. For  $\lambda = 0$ , we have

$$\left[ \begin{array}{ccc|c} 2 & 0 & 0 & 0 \\ -4 & -4 & 2 & 0 \\ -8 & -12 & 6 & 0 \end{array} \right] \rightsquigarrow \left[ \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 2 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right],$$

so eigenvectors are of the form

$$\begin{bmatrix} 0 \\ r/2 \\ r \end{bmatrix} = \frac{r}{2} \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}.$$

For  $\lambda = 2$ , we have

$$\left[ \begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ -4 & -6 & 2 & 0 \\ -8 & -12 & 4 & 0 \end{array} \right] \rightsquigarrow \left[ \begin{array}{ccc|c} 2 & 3 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right],$$

so eigenvectors are of the form

$$\begin{bmatrix} \frac{r}{2} - \frac{3s}{2} \\ s \\ r \end{bmatrix} = \frac{r}{2} \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} + \frac{s}{2} \begin{bmatrix} -3 \\ 2 \\ 0 \end{bmatrix}.$$

Thus we have, for instance, that

$$P = \begin{bmatrix} 0 & 1 & -3 \\ 1 & 0 & 2 \\ 2 & 2 & 0 \end{bmatrix} \quad D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}.$$

5. For each of the following twelve statements, indicate clearly whether it is true or false. (Assume  $A$  and  $B$  are square matrices of the same size.) For TWO of the statements, also do the following (in the space at the bottom of the page): If the statement is true, then explain why. If the statement is false, then provide a counterexample.

(a) \_\_\_\_\_ The matrix  $\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$  is diagonalizable.

False. Because it's upper triangular, the eigenvalues are  $\lambda = 0$  and  $\lambda = 1$ . The only eigenvalue that can be defective is  $\lambda = 1$  (it's the only one with multiplicity greater than one). Subtracting 1 from the diagonal and row-reducing gives  $\begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ , whose null-space is only one-dimensional.

(b) \_\_\_\_\_ If  $\det(A) = 0$ , then  $A$  has at least two equal rows.

False. This is just one of many reasons a matrix may have determinant zero.

(c) \_\_\_\_\_ If  $B$  is invertible, then  $\det(B^{-1}A) = \frac{\det(A)}{\det(B)}$

True. This follows from the facts that  $\det(AB) = \det(A)\det(B)$  and  $\det(A^{-1}) = (\det(A))^{-1}$ .

(d) \_\_\_\_\_  $A$  is singular if and only if  $\det(A) = 0$ .

True. This is a theorem.

(e) \_\_\_\_\_ If  $B$  is the row-reduced echelon form of  $A$ , then  $\det(A) = \det(B)$ .

False. All matrices with non-zero determinant row-reduce to the identity, which has determinant one.

(f) \_\_\_\_\_  $\det(A + B) = \det(A) + \det(B)$ .

False. Most random matrices will fail to satisfy this equality.

(g) \_\_\_\_\_ A matrix is diagonalizable if and only if it is nonsingular.

False. The zero matrix is singular but diagonalizable. The matrix  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$  is non-singular but non-diagonalizable.

(h) \_\_\_\_\_ Every  $3 \times 3$  matrix has at least one real eigenvalue.

True. Eigenvalues are roots of polynomials. A  $3 \times 3$  matrix has a cubic polynomial, which always has a real root (either because complex roots come in pairs, or because all degree-3 curves must cross the  $x$ -axis somewhere).

(i) \_\_\_\_\_ If all the eigenvalues of a matrix are real, then the matrix is diagonalizable.

False. An eigenvalue might be defective. Our standard non-diagonalizable matrix  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$  has all real eigenvalues, for example.

(j) \_\_\_\_\_ Any two eigenvectors corresponding to distinct eigenvalues of a symmetric matrix are orthogonal.

True. This is a theorem.

(k) \_\_\_\_\_ Zero is not allowed to be an eigenvalue.

False. The matrix in problem #3 has zero as an eigenvalue, for example. Eigenvectors are not allowed to be the zero vector, however.

(l) \_\_\_\_\_ Upper triangular matrices are always diagonalizable.

False. Our standard non-diagonalizable example is  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ , for example. The matrix in (a) is also a counterexample.