

1. [9 pts] You are given the following vector and two ordered bases for \mathbf{R}^3 :

$$S = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 3 \end{bmatrix} \right\} \quad T = \left\{ \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\} \quad \mathbf{v} = \begin{bmatrix} 7 \\ -1 \\ 9 \end{bmatrix}$$

(a) Find the coordinate vectors $[\mathbf{v}]_T$ and $[\mathbf{v}]_S$ directly.

For $[\mathbf{v}]_T$, we have the following:

$$\left[\begin{array}{ccc|c} 2 & 1 & 0 & 7 \\ 1 & 0 & 1 & -1 \\ 0 & 3 & 0 & 9 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|c} 2 & 1 & 0 & 7 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & -3 \end{array} \right]$$

which has solution

$$[\mathbf{v}]_T = \begin{bmatrix} 2 \\ 3 \\ -3 \end{bmatrix}.$$

For $[\mathbf{v}]_S$, we have the following:

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 7 \\ 0 & 1 & 1 & -1 \\ 1 & -2 & 3 & 9 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|c} 1 & 0 & 0 & 7 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 5 & 0 \end{array} \right]$$

which has solution

$$[\mathbf{v}]_S = \begin{bmatrix} 7 \\ -1 \\ 0 \end{bmatrix}.$$

(b) Find the transition matrix $P_{S \leftarrow T}$.

We need to find the S -coordinates for each of the T -basis vectors. Solving all three systems simultaneously, (and going all the way to reduced row-echelon form for convenience) we have the following:

$$\left[\begin{array}{ccc|c|c|c} 1 & 0 & 0 & 2 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 1 \\ 1 & -2 & 3 & 0 & 3 & 0 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|c|c|c} 1 & 0 & 0 & 2 & 1 & 0 \\ 0 & 1 & 0 & 1 & -2/5 & 3/5 \\ 0 & 0 & 1 & 0 & 2/5 & 2/5 \end{array} \right]$$

It follows that

$$P_{S \leftarrow T} = \begin{bmatrix} 2 & 1 & 0 \\ 1 & -2/5 & 3/5 \\ 0 & 2/5 & 2/5 \end{bmatrix}.$$

(c) Verify your answers to parts (a) and (b) by checking that

$$[\mathbf{v}]_S = P_{S \leftarrow T} [\mathbf{v}]_T.$$

$$\begin{bmatrix} 2 & 1 & 0 \\ 1 & -2/5 & 3/5 \\ 0 & 2/5 & 2/5 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \\ -3 \end{bmatrix} = \begin{bmatrix} 7 \\ -1 \\ 0 \end{bmatrix}$$

2. [3 pts] Let $T = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ be a basis for \mathbf{R}^2 . Given that $P_{S \leftarrow T} = \begin{bmatrix} 2 & 3 \\ -1 & 2 \end{bmatrix}$, find the basis S for \mathbf{R}^2 .

The columns of $P_{S \leftarrow T}$ are the S -coordinates of the T -basis vectors. Thus if we denote the S -basis by $\{\mathbf{v}_1, \mathbf{v}_2\}$, then we have

$$2\mathbf{v}_1 - \mathbf{v}_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{and} \quad 3\mathbf{v}_1 + 2\mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

Treating this as two equations in two unknowns (\mathbf{v}_1 and \mathbf{v}_2), we solve to find that

$$\mathbf{v}_1 = \begin{bmatrix} 3/7 \\ 1/7 \end{bmatrix} \quad \mathbf{v}_2 = \begin{bmatrix} -1/7 \\ 2/7 \end{bmatrix}.$$

Note that you also could have come up with four equations in four unknowns (two for each spot in each of the vectors).

3. [3 pts] Let $S = \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ be a basis for \mathbf{R}^2 . Given that $P_{S \leftarrow T} = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$, find the basis T for \mathbf{R}^2 .

This is easier than the previous one. The columns of $P_{S \leftarrow T}$ are precisely the S -coordinates of the T -basis vectors. Because we already have the S -basis, we just put the coordinates in front as coefficients to find the T -basis vectors. Thus we have

$$T = \left\{ 1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}, 2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\} = \left\{ \begin{bmatrix} 3 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ 1 \end{bmatrix} \right\}.$$

4. [6 pts] Let $L : \mathbf{R}^3 \rightarrow \mathbf{R}^3$ be defined by $L \left(\begin{bmatrix} a \\ b \\ c \end{bmatrix} \right) = \begin{bmatrix} 2a - c \\ a + b - c \\ c \end{bmatrix}$.

(a) Find the matrix representation for L with respect to the basis $S = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$.

We first plug the S -basis vectors into L , obtaining

$$L\left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad L\left(\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \quad L\left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}.$$

Now we take these outputs and find their S -coordinate vectors. Note that the first and third are already S -vectors themselves, so we clearly have

$$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}_S = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}_S = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

For the second output vector, we find the coordinates by solving as follows:

$$\left[\begin{array}{ccc|c} 1 & 0 & 1 & -1 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|c} 1 & 0 & 1 & -1 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 1 & 1 \end{array} \right]$$

so that

$$\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}_S = \begin{bmatrix} -2 \\ 2 \\ 1 \end{bmatrix}.$$

It follows that the matrix we seek is

$$\begin{bmatrix} 1 & -2 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 1 \end{bmatrix}.$$

(b) Suppose $[\mathbf{v}]_S = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$. Use your answer to part (a) to find $[L(\mathbf{v})]_S$ and $L(\mathbf{v})$.

Using the definition of what the matrix we found above actually does, we have

$$\begin{bmatrix} 1 & -2 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} -3 \\ 4 \\ 3 \end{bmatrix} = [L(\mathbf{v})]_S,$$

so

$$L(\mathbf{v}) = -3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + 4 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 4 \end{bmatrix}.$$

(By the way, \mathbf{v} is $\begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$.)