

Coordinates, Transition Matrices, and Matrix Representations

Notation: To simplify things, we'll assume V is 3-dimensional and W is 2-dimensional, just so we can be more explicit in the notation. Of course, all of this generalizes in obvious ways to spaces of any finite dimension.

We let $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ and $S' = \{\mathbf{v}'_1, \mathbf{v}'_2, \mathbf{v}'_3\}$ be bases for V , and $T = \{\mathbf{w}_1, \mathbf{w}_2\}$ and $T' = \{\mathbf{w}'_1, \mathbf{w}'_2\}$ be bases for W .

Remark: On this handout, the notation $[\mathbf{v}]$ (i.e., looks like coordinates but without any subscript specifying a basis) means the coordinates with respect to the standard basis of V (or W , as the case may be). In particular, if $V = \mathbf{R}^n$, then $[\mathbf{v}]$ means just the original column vector \mathbf{v} itself.

◇COORDINATE VECTOR: $[\mathbf{v}]_S = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$

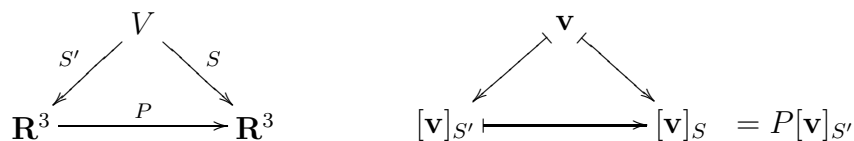
MEANS: $\mathbf{v} = a\mathbf{v}_1 + b\mathbf{v}_2 + c\mathbf{v}_3$

◇TRANSITION MATRIX: $P_{S \leftarrow S'}$

IS: $\begin{bmatrix} | & | & | \\ [\mathbf{v}'_1]_S & [\mathbf{v}'_2]_S & [\mathbf{v}'_3]_S \\ | & | & | \end{bmatrix}$

DOES: $[\mathbf{v}]_S = P_{S \leftarrow S'}[\mathbf{v}]_{S'}$

PICTURE:



IS FOUND BY: $\begin{bmatrix} | & | & | & | & | & | & | \\ [\mathbf{v}_1] & [\mathbf{v}_2] & [\mathbf{v}_3] & | & [\mathbf{v}'_1] & [\mathbf{v}'_2] & [\mathbf{v}'_3] \\ | & | & | & | & | & | & | \end{bmatrix} \rightsquigarrow [I_3 \mid P_{S \leftarrow S'}]$

◇MATRIX REPRESENTATION: A representing $L : V \rightarrow W$ w.r.t. S and T

$$\text{IS: } \left[\begin{array}{c|c|c} | & | & | \\ [L(\mathbf{v}_1)]_T & [L(\mathbf{v}_2)]_T & [L(\mathbf{v}_3)]_T \\ | & | & | \end{array} \right]$$

$$\text{DOES: } A[\mathbf{v}]_S = [L(\mathbf{v})]_T$$

PICTURE:

$$\begin{array}{ccc} V & \xrightarrow{L} & W \\ s \downarrow & & \downarrow T \\ \mathbf{R}^3 & \xrightarrow{A} & \mathbf{R}^2 \end{array} \qquad \begin{array}{ccc} \mathbf{v} & \xrightarrow{\quad} & L(\mathbf{v}) \\ \downarrow & & \downarrow \\ [\mathbf{v}]_S & \xrightarrow{\quad} & [L(\mathbf{v})]_T = A[\mathbf{v}]_S \end{array}$$

$$\text{IS FOUND BY: } \left[\begin{array}{c|c|c|c|c} | & | & | & | & | \\ [\mathbf{w}_1] & [\mathbf{w}_2] & [L(\mathbf{v}_1)] & [L(\mathbf{v}_2)] & [L(\mathbf{v}_3)] \\ | & | & | & | & | \end{array} \right] \rightsquigarrow [I_2 \mid A]$$

◇RELATING MATRIX REPRESENTATIONS: $B = Q^{-1}AP$

$$\begin{array}{ccc} \mathbf{R}^3 & \xrightarrow{B} & \mathbf{R}^2 \\ & \swarrow S' & \nearrow T' \\ & V & \xrightarrow{L} & W \\ & \swarrow S & \searrow T & \\ \mathbf{R}^3 & \xrightarrow{A} & \mathbf{R}^2 \end{array} \quad \begin{array}{c} P \\ \downarrow \\ \mathbf{R}^3 \\ \downarrow \\ \mathbf{R}^2 \\ Q \end{array}$$

$$\begin{array}{ccc} [\mathbf{v}]_{S'} & \xrightarrow{\quad} & [L(\mathbf{v})]_{T'} = B[\mathbf{v}]_{S'} = Q^{-1}A[\mathbf{v}]_{S'} \\ \downarrow & \swarrow & \nearrow \\ & \mathbf{v} & \xrightarrow{\quad} & L(\mathbf{v}) \\ & \swarrow & \searrow & \\ [\mathbf{v}]_S & \xrightarrow{\quad} & [L(\mathbf{v})]_T = A[\mathbf{v}]_S \end{array}$$