

Digital Interfacing

EE 264
Dr. Samuel Russ

Why do microprocessors need interface circuits?

- ◆ Drive strength
 - Single microprocessor pin can generally only drive a small number of outputs
 - Example: Not strong enough to drive a single LED!
- ◆ Voltage differences
 - Different digital devices run at different voltage levels
 - Examples: 5V, 3.3V, 2.5V, $\pm 12V$, etc.
- ◆ Safety issues
 - Lightning
 - Other extremely high voltages

Drive-Strength: Drivers

- ◆ Special buffers that have high output current
- ◆ Example: Clock driver – Has built-in circuits to synchronize the output to the input (0 delay)
- ◆ LED: 10's of mA
- ◆ Relay: 100's of mA

Voltage-Level Change

- ◆ One-way: Open-drain drivers
 - These also increase drive strength
 - Only drive to ground (0V) which is a nearly "universal" voltage level
- ◆ Two-way: Pass transistor circuits
 - Lets either side drive to ground (bidirectional)
- ◆ RS-232 driver circuit
 - Special case: Drives $\pm 12V$ outputs off of a single +5V supply

Isolation / Safety Circuits

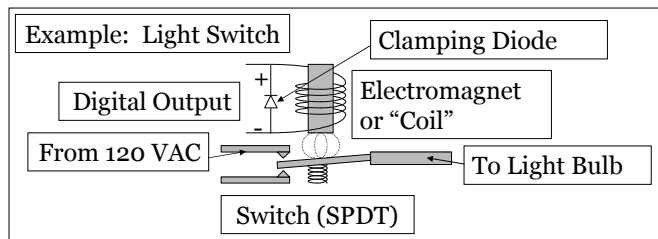
- ◆ Isolation: Provide voltage isolation between input and output
- ◆ Protection: Two forms
 - Disconnects power when current draw is too large
 - Shorts out and dissipates when voltage rises above a certain level

Specific Examples of Driver Circuits

- ◆ Highlights choices available to digital-system designers
- ◆ Consult datasheets – and feel free to find your own solutions!

Common Example: Electromechanical Relay

- ◆ Digital output drives an electromagnet
- ◆ The magnet moves a switch back and forth between contacts

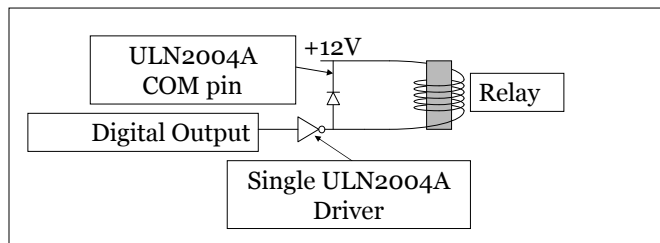


Relays, ctd.

- ◆ The switch is a simple short-circuit
 - Can be AC, DC, radio-frequency, etc.
- ◆ Switch is completely isolated from the digital driver – no DC connection
- ◆ The coil produces an inductive “kick” when it is open-circuited
 - Attach a diode from – to + to absorb the energy
- ◆ Coil voltages: +5V, +12V
- ◆ Coil currents: 10’s to 100’s of mA

High Drive Strength: ULN2004A

- ◆ Array of 7 Darlington-Pair Open-Collector drivers
- ◆ Each output can sink 350 mA
- ◆ Built-in diodes to drive relays

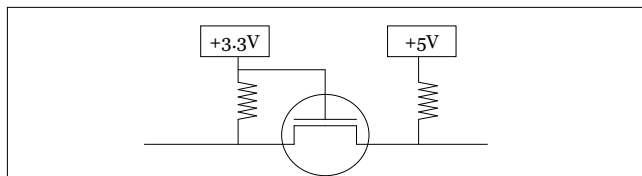


High Drive Strength: TI TPIC Logic

- ◆ Each output can drive 100's of mA
- ◆ Example: TPIC6595 is a shift register
 - Three-bit input, 8 output drivers
 - Cascadable to dozens of output drivers
- ◆ Combines low pin count with high drive strength

Voltage-Level Conversion: Pass-Transistor Isolation

- ◆ Use N-channel MOSFET: Lets either side drive to ground
 - Bi-directional interface
 - Need pull-up resistors to drive high
- ◆ Example: 3.3V and 5V



Voltage-Level Conversion: RS-232 Driver

- ◆ Maxim MAX232 is designed to drive RS-232 $\pm 12V$ using a single +5V supply
 - Has built in voltage drivers to create +12V and -12V given only +5V
 - Other variations of the part do similar things
 - Go get the datasheets!

Voltage Isolation: Opto-Isolators

- ◆ Opto-isolators are combinations of LED's (or IRED's) and photocells
- ◆ No DC connection from input to output – only photons!
- ◆ Typical isolation is 3,500 volts
- ◆ Output can be DC or AC
 - DC type: Darlington-pair output
 - AC type: Triac output

Other Safety Devices

- ◆ One type is the simplest: The Fuse!
 - Numerous variations, such as slow-blow
 - Provides a current limit on the system
- ◆ Several devices turn into short circuits
 - Telephony: Sidactors
 - Power strips (etc.): Metal-Oxide Varistors (MOV's)
- ◆ I don't like MOV's: They can burst into flame!!
 - Adding current limits makes this more likely!
- ◆ Needless to say, **READ THE DATASHEET** when designing for safety!